



Conceptual study on Flexible Guidance and Docking system for ITER Remote Handling Transport Cask

ERB 5004 CT 96 0127-NET96-431 (EFDA) | [1996-1997]

○ Partners

- Instituto Superior Técnico (IST), Portugal

○ Objectives

- Study of a concept, different from rail-based, to transport the casks containing divertors and blanket modules from the Tokamak Building to the Hot Cell Building

○ Addressed topics

- Flexible Guidance and Navigation Methodologies
- Traction and kinematics structures of mobile robots
- Guidance and Navigation strategies
- Communications
- Docking

○ Concept proposed by IST (AGV + free roaming platform)

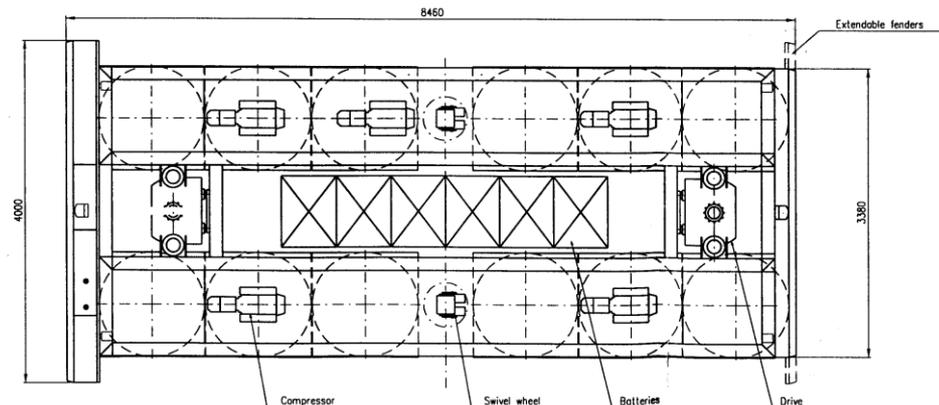
- Flexible guidance vehicle with a **rombic kinematic** structure (two drive and steering wheels) with:
 - **Inductive steering** for primary guidance (AGV solution)
 - **Free-roaming navigation** for secondary guidance (mobile robot)
- Equipped with **air-cushions**

selected in 1997 by ITER JCT as **the reference concept for transport** of components between TB and HCB

○ Air-cushion platform



- 12 aero-casters
- 5 compressors
- 6 battery packs





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○ Publications from IST team:

- Isabel Ribeiro, Pedro Lima, Pedro Aparício, Renato Ferreira, “Conceptual Study on Flexible Guidance and Navigation for ITER Remote Handling Transport Casks”, Proceedings of the 17th IEEE/NPSS Symposium on Fusion Engineering, San Diego, USA October 1997, pp. 969-972.
- Isabel Ribeiro, Pedro Lima, Pedro Aparício, Renato Ferreira Conceptual Study on Flexible Guidance, Navigation and Docking Systems for the ITER RH Transport Casks, ISR Internal Report RT-401-97, 1997 – [PDF](#)